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DOCUMENT

Earth Observation Mission Software File Format Specification

| | |
|----------------------|-----------------------------|
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1 INTRODUCTION

This document describes the format of some of the files used within Earth Observation Ground Segment Facilities. Formats are described for the file types listed in Table 1. These files are compliant with Earth Observation Ground Segment File Format Standard (FFS), see [RD01].

The “Format Version“ is a number keeping track of format modifications. The formats defined by the Format Versions mentioned in Table 1 are compliant with FFS v3.0.

| File Type | Content | Format Version |
|----------------------------------|--|----------------|
| Orbit State Vector File | List of Orbit State Vectors (i.e. position and velocity at given times) | 3.0 |
| Orbit Scenario File | Set of parameters describing an orbit, e.g. repeat cycle, cycle length, MLST | 3.1 |
| Satellite Configuration File | Set of parameters describing an orbit, e.g. keplerian elements | 3.0 |
| Attitude Quaternion File | List of quaternions at given times | 3.1 |
| Attitude Roll Pitch Yaw File | List of roll pitch yaw angles at given times | 3.1 |
| Swath Definition File | Set of parameters defining an instrument swath | 4.0 |
| Swath Template File | One or more lists of latitude, longitude points defining a swath footprint | 4.0 |
| Zone Database File | One or more lists of latitude, longitude points defining zones (e.g. polygons) | 3.0 |
| Station Database File | One or more set of parameters defining Ground Stations | 3.0 |
| Attitude Definition File | Set of data or models defining satellite attitude | 3.1 |
| Field of View Configuration File | Set of parameters (e.g. list of azimuth, elevation) defining a field of view | 3.0 |

Table 1 – list of Earth Observation Ground Segment Files

References

| Id | Title |
|--------|--|
| [RD01] | Earth Observation Ground Segment File Format Standard (version 3.0), http://eop-cfi.esa.int/Repo/PUBLIC/DOCUMENTATION/SYSTEM_SUPPORT_DOCS/PE-TN-ESA-GS-0001%20EO%20GS%20File%20Format%20Standard%203.0.pdf |
| [RD02] | Handbook for EO XML and Binary Schemas (version 1.7.1), http://eop-cfi.esa.int/Repo/PUBLIC/DOCUMENTATION/SYSTEM_SUPPORT_DOCS/PE-TN-ESA-GS-121%20%20Handbook%20for%20EO%20XML%20and%20Binary%20Schemas%201.7.1.pdf |
| [RD03] | Earth Observation Ground Segment File Format Standard (version 2.0), http://eop-cfi.esa.int/Repo/PUBLIC/DOCUMENTATION/SYSTEM_SUPPORT_DOCS/PE-TN-ESA-GS-0001%20EO%20GS%20File%20Format%20Standard%202.0.pdf |



2 COMPLIANCE WITH FILE FORMAT STANDARD

The File Format Standard (FFS) defines a structure common to all files used within the Earth Observation Ground Segment. More details can be found in [RD01].

Figure 1 shows the skeleton of a file compliant with FFS v3.0. The file shall be written according to XML syntax and shall follow certain conventions for file naming. It shall be composed by a Fixed Header (enclosed within **Fixed_Header** tags), a Variable Header (enclosed within **Variable_Header** tags), and a Data Block (enclosed within **Data_Block** tags). Only Variable Header and Data Block content depends on the file type. The file shall reference to an XML schema for validation via dedicated attributes in the **Earth_Observation_File** element as described in section 7.3 of [RD02]. Such attributes are:

- `xsi:schemaLocation` : the validating schema URL
- `schemaVersion` : the validating schema version

The validating schema version is encoded in the schema filename (e.g. version 1.5 is encoded as 0105 in `EO_OPER_MPL_ORBRES_0105.XSD`).

The validating schema version is identical to the File Format Version (e.g. the validating schema for Orbit Scenario File Format version 3.1 is named `EO_OPER_MPL_ORBSCT_0301.XSD`).

```
<?xml version="1.0" encoding="UTF-8"?>
<Earth_Observation_File xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
xsi:schemaLocation="..." schemaVersion="..." xmlns="http://eop-cfi.esa.int/CFI">
  <Earth_Observation_Header>
    <Fixed_Header>
      <File_Name>...</File_Name>
      <File_Description>...</File_Description>
      <Notes> ... </Notes>
      <Mission>...</Mission>
      <File_Class>...</File_Class>
      <File_Type>...</File_Type>
      <Validity_Period>
        <Validity_Start>...</Validity_Start>
        <Validity_Stop>...</Validity_Stop>
      </Validity_Period>
      <File_Version>...</File_Version>
      <EOFFS_Version>...</EOFFS_Version>
      <Source>
        <System>...</System>
        <Creator>...</Creator>
        <Creator_Version>...</Creator_Version>
        <Creation_Date>...</Creation_Date>
      </Source>
    </Fixed_Header>
    <Variable_Header>
      ...
    </Variable_Header>
  </Earth_Observation_Header>
  <Data_Block type="xml">
    ...
  </Data_Block>
</Earth_Observation_File>
```

Figure 1 – Skeleton of file compliant with FFS

Figure 2 shows the skeleton of a file compliant with FFS v2.0 (see [RD03]) and v1.0. The main difference between FFS v3.0 and previous versions v2.0 and v1.0 is the use of the **Earth_Explorer_File** and **Earth_Explorer_Header** elements. The **EOFFS_Version** element is used only in FFS v3.0.

```
<?xml version="1.0" encoding="UTF-8"?>
<Earth_Explorer_File xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
xsi:schemaLocation="..." schemaVersion="..." xmlns="http://eop-cfi.esa.int/CFI">
  <Earth_Explorer_Header>
    <Fixed_Header>
      <File_Name>...</File_Name>
      <File_Description>...</File_Description>
      <Notes> ... </Notes>
      <Mission>...</Mission>
      <File_Class>...</File_Class>
      <File_Type>...</File_Type>
      <Validity_Period>
        <Validity_Start>...</Validity_Start>
        <Validity_Stop>...</Validity_Stop>
      </Validity_Period>
      <File_Version>...</File_Version>
      <Source>
        <System>...</System>
        <Creator>...</Creator>
        <Creator_Version>...</Creator_Version>
        <Creation_Date>...</Creation_Date>
      </Source>
    </Fixed_Header>
    <Variable_Header>
      ...
    </Variable_Header>
  </Earth_Explorer_Header>
  <Data_Block type="xml">
    ...
  </Data_Block>
</Earth_Explorer_File>
```

Figure 2 – Skeleton of file compliant with FFS legacy versions

The main difference between FFS v2.0 and FFS v1.0 is in file naming. In FFS v3.0 and v2.0, the mission identifier is composed by three letters and the file extension is EOF (e.g. **S1A_TEST_AUX_ORBRES_20200401T040000_20200401T041000_0001.EOF**)

In FFS v1.0, the mission identifier is composed by two letters and the file extension is EEF (e.g. **CS_TEST_AUX_ORBRES_20200401T040000_20200401T041000_0001.EEF**)

Table 2 provides, for each File Type and File Format Standard Version, the latest File Format Version and the relevant validating schema. Validating schemas can be found at: <http://eop-cfi.esa.int/CFI>

| File Type | FFS Version | File Format Version | Validating schema |
|--|-------------|---------------------|-----------------------------|
| Orbit State Vector File | 1.0 | 1.5 | EO_OPER_AUX_ORBRES_0105.XSD |
| | 2.0 | 2.3 | EO_OPER_AUX_ORBRES_0203.XSD |
| | 3.0 | 3.0 | EO_OPER_AUX_ORBRES_0300.XSD |
| Orbit Scenario File | 1.0 | 1.6 | EO_OPER_MPL_ORBSCT_0106.XSD |
| | 2.0 | 2.5 | EO_OPER_MPL_ORBSCT_0205.XSD |
| | 3.0 | 3.1 | EO_OPER_MPL_ORBSCT_0301.XSD |
| Satellite Configuration File | 1.0 | 1.3 | EO_OPER_INT_SATCFG_0103.XSD |
| | 2.0 | 2.2 | EO_OPER_INT_SATCFG_0202.XSD |
| | 3.0 | 3.0 | EO_OPER_INT_SATCFG_0300.XSD |
| Attitude Quaternion File Attitude Roll Pitch Yaw File | 1.0 | 1.4 | EO_OPER_INT_ATTREF_0104.XSD |
| | 2.0 | 2.4 | EO_OPER_INT_ATTREF_0204.XSD |
| | 3.0 | 3.1 | EO_OPER_INT_ATTREF_0301.XSD |
| Swath Definition File | 1.0 | 2.4 | EO_OPER_MPL_SW_DEF_0204.XSD |
| | 2.0 | 3.4 | EO_OPER_MPL_SW_DEF_0304.XSD |
| | 3.0 | 4.1 | EO_OPER_MPL_SW_DEF_0401.XSD |
| Swath Template File | 1.0 | 2.3 | EO_OPER_MPL_SWTREF_0203.XSD |
| | 2.0 | 3.3 | EO_OPER_MPL_SWTREF_0303.XSD |
| | 3.0 | 4.0 | EO_OPER_MPL_SWTREF_0400.XSD |
| Zone Database File | 1.0 | 1.3 | EO_OPER_MPL_ZON_DB_0103.XSD |
| | 2.0 | 2.2 | EO_OPER_MPL_ZON_DB_0202.XSD |
| | 3.0 | 3.0 | EO_OPER_MPL_ZON_DB_0300.XSD |
| Station Database File | 1.0 | 1.5 | EO_OPER_MPL_GND_DB_0105.XSD |
| | 2.0 | 2.2 | EO_OPER_MPL_GND_DB_0202.XSD |
| | 3.0 | 3.0 | EO_OPER_MPL_GND_DB_0300.XSD |
| Attitude Definition File | 1.0 | 1.4 | EO_OPER_INT_ATTDEF_0104.XSD |
| | 2.0 | 2.5 | EO_OPER_INT_ATTDEF_0205.XSD |
| | 3.0 | 3.2 | EO_OPER_INT_ATTDEF_0302.XSD |
| Field of View Configuration File | 1.0 | 1.0 | EO_OPER_INT_FOVCFG_0100.XSD |
| | 2.0 | 2.0 | EO_OPER_INT_FOVCFG_0200.XSD |
| | 3.0 | 3.0 | EO_OPER_INT_FOVCFG_0300.XSD |

Table 2 – Mapping between File Types, FFS Version, File Format Version and validating schemas

3 FILE FORMAT SPECIFICATION

The following sections describe, for each file type:

- the content of the Variable Header;
- the content of the Data Block;
- the reference to the validating schema for FFS v3.0 (shortly named “Schema Reference”).

3.1 Orbit State Vector File

3.1.1 Variable Header

The Variable Header content is a sequence of XML elements described in Table 3.

| XML Tag name | Type | Attributes | C Format | Description |
|----------------|--------|------------|----------|---|
| Ref_Frame | string | - | %s | Orbit State Vector (see Table 5) co-ordinate system reference frame, it can be one of the following values: GEO_MEAN_2000 MEAN_DATE TRUE_DATE EARTH_FIXED |
| Time_Reference | string | - | %s | Time reference used when, due to an inconsistency with other time correlations, times associated to the state vector have to be recomputed. It can be one of the following values: TAI UTC UT1 |

Table 3 – Variable Header content

Example:

```
<Variable_Header>
  <Ref_Frame>EARTH_FIXED</Ref_Frame>
  <Time_Reference>UTC</Time_Reference>
</Variable_Header>
```

3.1.2 Data Block

The Data Block content is a sequence of XML elements described in Table 4.

| XML Tag name | Type | Attributes | C Format | Description |
|--------------|-------------|--|----------|-------------------------------------|
| List_of_OSVs | XML element | count="N" where n is the number of elements in the list | - | List of OSV elements (see Table 5). |

Table 4 – Data Block content

| XML Tag name | Type | Attributes | C Format | Description |
|----------------|---------|------------|-----------|---|
| TAI | string | - | - | TAI date and time of OSV, in ASCII standard time format, including time reference and microseconds: TAI=yyyy-mm-ddThh:mm:ss.ssssss |
| UTC | string | - | - | UTC date and time of OSV, in ASCII standard time format, including time reference and microseconds: UTC=yyyy-mm-ddThh:mm:ss.ssssss |
| UT1 | string | - | - | UT1 date and time of OSV, in ASCII standard time format, including time reference and microseconds: UT1=yyyy-mm-ddThh:mm:ss.ssssss |
| Absolute_Orbit | integer | - | %+06ld | Absolute Orbit Number of the OSV |
| X | real | unit="m" | %+012.3lf | X component of the OSV position vector in m with a precision of 1e-3. |
| Y | real | unit="m" | %+012.3lf | Y component of the OSV position vector in m with a precision of 1e-3. |
| Z | real | unit="m" | %+012.3lf | Z component of the OSV position vector in m with a precision of 1e-3. |
| VX | real | unit="m/s" | %+012.6lf | X component of the OSV velocity vector in m/s with a precision of 1e-6. |
| VY | real | unit="m/s" | %+012.6lf | Y component of the OSV velocity vector in m/s with a precision of 1e-6. |
| VZ | real | unit="m/s" | %+012.6lf | Z component of the OSV velocity vector in m/s with a precision of 1e-6. |
| Quality | string | - | %13s | This parameter is added to keep format compatibility with legacy formats. Default ("not used") value is "0000000000000" |

Table 5 – OSV element content

Example (only the first and last OSVs are shown):

```

<Data_Block type="xml">
  <List_of_OSVs count="243">
    <OSV>
      <TAI>TAI=2021-06-10T04:57:17.817060</TAI>
      <UTC>UTC=2021-06-10T04:57:52.817060</UTC>
      <UT1>UT1=2021-06-10T04:57:53.117059</UT1>
      <Absolute_Orbit>+00999</Absolute_Orbit>
      <X unit="m">-1606749.988</X>
      <Y unit="m">-5677008.966</Y>
      <Z unit="m">-4135675.595</Z>
      <VX unit="m/s">-2876.652288</VX>
      <VY unit="m/s">-3541.028256</VY>
      <VZ unit="m/s">+5985.303441</VZ>
      <Quality>00000000000000</Quality>
    </OSV>
    [...]
    <OSV>
      <TAI>TAI=2021-06-10T06:58:17.817060</TAI>
      <UTC>UTC=2021-06-10T06:58:52.817060</UTC>
      <UT1>UT1=2021-06-10T06:58:53.117059</UT1>
      <Absolute_Orbit>+01001</Absolute_Orbit>
      <X unit="m">-5075578.371</X>
      <Y unit="m">-3158584.535</Y>
      <Z unit="m">+4005164.344</Z>
      <VX unit="m/s">+2519.609604</VX>
      <VY unit="m/s">+3677.868542</VY>
    </OSV>
  </List_of_OSVs>
</Data_Block>

```



```
<VZ unit="m/s">+6075.683811</VZ>
<Quality>0000000000000</Quality>
</OSV>
</List_of_OSVs>
</Data_Block>
```

3.1.3 Schema Reference

An example of validating XML schema for this file type is located at:
http://eop-cfi.esa.int/CFI/EE_CFI_SCHEMAS/EO_OPER_AUX_ORBRES_0300.XSD

This schema is compliant to [RD02] and includes format and range checks to ensure compliance to this specification and to the File Format Standard [RD01]. The schema file is named according to section 6.1.1 in [RD02] and is applicable to files named `MMM_OPER_AUX_ORBRES_<instance_id>.EOF`.

The following is the content of the [Earth_Observation_File](#) required to reference the above schema.

```
<Earth_Observation_File xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
xsi:schemaLocation="http://eop-cfi.esa.int/CFI http://eop-
cfi.esa.int/CFI/EE_CFI_SCHEMAS/EO_OPER_AUX_ORBRES_0300.XSD"
schemaVersion="3.0" xmlns="http://eop-cfi.esa.int/CFI">
```



3.2 Orbit Scenario File

3.2.1 Variable Header

The Variable Header content is a sequence of XML elements described in Table 6.

| XML Tag name | Type | Attributes | C Format | Description |
|----------------|--------|------------|----------|---|
| Time_Reference | string | - | %s | Time reference used when, due to an inconsistency with other time correlations, times associated to the state vector have to be recomputed. It can be one of the following values: UT1 |

Table 6 – Variable Header content

Example:

```
<Variable_Header>
  <Time_Reference>UTC</Time_Reference>
</Variable_Header>
```

3.2.2 Data Block

The Data Block content is a sequence of XML elements described in Table 7.

| XML Tag name | Type | Attributes | C Format | Description |
|-----------------------|-------------|--|----------|--|
| List_of_Orbit_Changes | XML element | count="N" where n is the number of elements in the list | - | List of Orbit_Change elements (see Table 8). |

Table 7 – Data Block content

| XML Tag name | Type | Attributes | C Format | Description |
|--------------|-------------|------------|----------|-------------------------------------|
| Orbit | XML element | - | - | Orbit information (see Table 9). |
| Cycle | XML element | - | - | Cycle information (see Table 10). |
| Time_of_ANX | XML element | - | - | Ascending node time (see Table 12). |

Table 8 – Orbit_Change element content

| XML Tag name | Type | Attributes | C Format | Description |
|----------------|---------|------------|----------|-----------------------|
| Absolute_Orbit | integer | - | %ld | absolute orbit number |
| Relative_Orbit | integer | - | %ld | relative orbit number |
| Cycle_Number | integer | - | %ld | cycle number |
| Phase_Number | integer | - | %ld | phase number |

Table 9 – Orbit element content

| XML Tag name | Type | Attributes | C Format | Description |
|----------------------|-------------|--------------|----------|---|
| Repeat_Cycle | integer | - | %ld | Repeat Cycle |
| Cycle_Length | integer | - | %ld | Cycle Length |
| ANX_Longitude | real | unit="deg" | %.6lf | longitude of ascending node crossing (ANX) in degrees with a resolution of 1e-6 degrees |
| ANX_Longitude_Drift | XML element | - | - | drift of ANX Longitude, see Table 11 |
| MLST | time | - | %s | mean local solar time at ANX of relative orbit 1 expressed as hours, minutes, seconds and microseconds HH:MM:SS.ssssss |
| MLST_Drift | real | unit="s/day" | %.6lf | drift of mean local solar time in s/day with a resolution of 1e-6 |
| MLST_Nonlinear_Drift | XML element | - | - | Non linear MLST data, see Table 12 |

Table 10 – Cycle element content

| XML Tag name | Type | Attributes | C Format | Description |
|--------------|------|----------------|----------|--|
| Offset | real | unit="deg" | %.6lf | ANX Longitude drift initial value in deg with a resolution of 1e-6 |
| Linear_Term | real | unit="deg/day" | %.6lf | ANX Longitude drift linear term in deg/day with a resolution of 1e-6 |

Table 11 – ANX_Longitude_Drift element content

| XML Tag name | Type | Attributes | C Format | Description |
|------------------------|-------------|--|----------|---|
| Linear_Approx_Validity | integer | unit="orbits" | %d | Number of orbits in which linear approximation is valid. |
| Quadratic_Term | real | unit="s/day^2" | %.6lf | MLST Quadratic term in s/day^2 with a resolution of 1e-6s/day^2. |
| Harmonics_Terms | XML element | num="N" where N is the number of harmonics (between 0 and 2) | - | List of Harmonics_Term elements (see Table 13). The Harmonics_Term element has a seq="i" attribute, where I denotes the identifier in the sequence starting from 1. |

Table 12 – MLST_Nonlinear_Drift element content

| XML Tag name | Type | Attributes | C Format | Description |
|----------------|--------|----------------|----------|--|
| Reference_Time | string | time_ref="UT1" | %s | UT1 Reference time of harmonic, in ASCII standard time format, including microseconds: yyyy-mm-ddThh:mm:ss.ssssss |
| Period | real | unit="days" | %6.2lf | Period of the harmonic in days with a resolution of 1e-2 days. |
| Amplitude_Sin | real | unit="sec" | %5.3lf | Amplitude of sine in seconds with a resolution of 1e-3 seconds |
| Amplitude_Cos | real | unit="sec" | %5.3lf | Amplitude of cosine in seconds with a resolution of 1e-3 seconds |

Table 13 – Harmonics_Term element content

| XML Tag name | Type | Attributes | C Format | Description |
|--------------|--------|------------|----------|---|
| TAI | string | - | %s | TAI date and time of ANX, in ASCII standard time format, including time reference and microseconds: TAI=yyyy-mm-ddThh:mm:ss.ssssss |
| UTC | string | - | %s | UTC date and time of ANX, in ASCII standard time |

| | | | | |
|-----|--------|---|----|---|
| | | | | format, including time reference and microseconds: UTC=yyyy-mm-ddThh:mm:ss.ssssss |
| UT1 | string | - | %s | UT1 date and time of ANX, in ASCII standard time format, including time reference and microseconds: UT1=yyyy-mm-ddThh:mm:ss.ssssss |
| TAI | string | - | %s | TAI date and time of ANX, in ASCII standard time format, including time reference and microseconds: TAI=yyyy-mm-ddThh:mm:ss.ssssss |

Table 14 – Time_of_ANX element content

Example:

```

<Data_Block type="xml">
  <List_of_Orbit_Changes count="1">
    <Orbit_Change>
      <Orbit>
        <Absolute_Orbit>1</Absolute_Orbit>
        <Relative_Orbit>11417</Relative_Orbit>
        <Cycle_Number>1</Cycle_Number>
        <Phase_Number>1</Phase_Number>
      </Orbit>
      <Cycle>
        <Repeat_Cycle unit="day">838</Repeat_Cycle>
        <Cycle_Length unit="orbit">11945</Cycle_Length>
        <ANX_Longitude unit="deg">40.300000</ANX_Longitude>
        <ANX_Longitude_Drift>
          <Offset unit="deg">0.010000</Offset>
          <Linear_Term unit="deg/day">0.000001</Linear_Term>
        </ANX_Longitude_Drift>
        <MLST>21:59:55.572000</MLST>
        <MLST_Drift unit="s/day">-0.270000</MLST_Drift>
        <MLST_Nonlinear_Drift>
          <Linear_Approx_Validity
unit="orbit">99999</Linear_Approx_Validity>
          <Quadratic_Term unit="s/day^2">0.000000</Quadratic_Term>
          <Harmonics_Terms num="1">
            <Harmonic_Term seq="1">
              <Reference_Time time_ref="UT1">2016-02-
17T00:00:00.000000</Reference_Time>
              <Period unit="days">10.00</Period>
              <Amplitude_Sin unit="sec">0.001</Amplitude_Sin>
              <Amplitude_Cos unit="sec">0.001</Amplitude_Cos>
            </Harmonics_Terms>
          </MLST_Nonlinear_Drift>
        </Cycle>
      </Orbit_Change>
    </List_of_Orbit_Changes>
  </Data_Block>

```

3.2.3 Schema Reference

An example of validating XML schema for this file type is located at:
http://eop-cfi.esa.int/CFI/EE_CFI_SCHEMAS/EO_OPER_MPL_ORBSCT_0301.XSD



This schema is compliant to [RD02] and includes format and range checks to ensure compliance to this specification and to the File Format Standard [RD01]. The schema file is named according to section 6.1.1 in [RD02] and is applicable to files named `MMM_OPER_MPL_ORBSCT_<instance_id>.EOF`.

The following is the content of the [Earth_Observation_File](#) required to reference the above schema.

```
<Earth_Observation_File xmlns:xsi=http://www.w3.org/2001/XMLSchema-instance
  xsi:schemaLocation="http://eop-cfi.esa.int/CFI
  http://eop-cfi.esa.int/CFI/EE_CFI_SCHEMAS/EO_OPER_MPL_ORBSCT_0301.XSD"
  schemaVersion="3.1"
  xmlns="http://eop-cfi.esa.int/CFI">
```


3.3 Satellite Configuration File

3.3.1 Variable Header

The Variable Header is empty for this type of file.

3.3.2 Data Block

The Data Block content is a sequence of XML elements described in Table 15.

| XML Tag name | Type | Attributes | C Format | Description |
|----------------|-------------|------------|----------|--|
| Satellite_Name | string | - | %s | Satellite Name |
| NORAD_Data | XML element | - | - | NORAD Satellite data, see Table 16 |
| Lib_Init | XML element | - | - | Low and tight tolerances for orbital parameters, see Table 17. |
| Orbit_Init | XML element | - | - | Default Orbital parameters, see Table 18 |

Table 15 – Data Block content

| XML Tag name | Type | Attributes | C Format | Description |
|------------------|---------|------------|----------|--------------------------------|
| Satellite_Number | integer | - | %ld | NORAD Satellite number |
| NORAD_Sat_Name | string | - | %s | NORAD Satellite name |
| Int_Designator | string | - | %s | NORAD international designator |

Table 16 – NORAD_Data element content

| XML Tag name | Type | Attributes | C Format | Description |
|------------------|-------------|------------|----------|---|
| Low_Tolerances | string | - | %s | Low tolerances for orbital parameters, see Table 19 |
| Tight_Tolerances | XML element | - | - | Tight tolerances for orbital parameters, see Table 19 |

Table 17 – Lib_Init element content

| XML Tag name | Type | Attributes | C Format | Description |
|---------------------|------|------------|----------|---------------------------------------|
| Min_Semi_Major_Axis | real | - | %lf | Minimum semi-major axis (meters) |
| Nom_Semi_Major_Axis | real | - | %lf | Nominal semi-major axis (meters) |
| Max_Semi_Major_Axis | real | - | %lf | Maximum semi-major axis (meters) |
| Min_Inclination | real | - | %lf | Minimum inclination (degrees) |
| Nom_Inclination | real | - | %lf | Nominal inclination (degrees) |
| Max_Inclination | real | - | %lf | Maximum inclination (degrees) |
| Nom_Eccentricity | real | - | %lf | Nominal Eccentricity |
| Nom_Arg_Perigee | real | - | %lf | Nominal Argument of perigee (degrees) |

Table 18 – Orbit_Init element content

| XML Tag name | Type | Attributes | C Format | Description |
|---------------------|------|------------|----------|----------------------------------|
| Min_Semi_Major_Axis | real | - | %lf | Minimum semi-major axis (meters) |
| Max_Semi_Major_Axis | real | - | %lf | Maximum semi-major axis (meters) |
| Min_Inclination | real | - | %lf | Minimum inclination (degrees) |
| Max_Inclination | real | - | %lf | Maximum inclination (degrees) |
| Min_Eccentricity | real | - | %lf | Minimum Eccentricity |
| Max_Eccentricity | real | - | %lf | Maximum Eccentricity |



| | | | | |
|---------------------|------|---|-----|----------------------------------|
| Min_Semi_Major_Axis | real | - | %lf | Minimum semi-major axis (meters) |
| Max_Semi_Major_Axis | real | - | %lf | Maximum semi-major axis (meters) |

Table 19 – Low_ and Tight_Tolerances element content

Example:

```

<Data_Block type="xml">
  <Satellite_Name>NEW_SATELLITE</Satellite_Name>
  <NORAD_Data>
    <Satellite_Number>1</Satellite_Number>
    <NORAD_Sat_Name>TBD</NORAD_Sat_Name>
    <Int_Designator>00000AAA</Int_Designator>
  </NORAD_Data>
  <Lib_Init>
    <Low_Tolerances>
      <Min_Semi_Major_Axis>7140000.000000</Min_Semi_Major_Axis>
      <Max_Semi_Major_Axis>7240000.000000</Max_Semi_Major_Axis>
      <Min_Inclination>98.290000</Min_Inclination>
      <Max_Inclination>99.110000</Max_Inclination>
      <Min_Eccentricity>0.0</Min_Eccentricity>
      <Max_Eccentricity>0.5</Max_Eccentricity>
    </Low_Tolerances>
    <Tight_Tolerances>
      <Min_Semi_Major_Axis>7150000.000000</Min_Semi_Major_Axis>
      <Max_Semi_Major_Axis>7230000.000000</Max_Semi_Major_Axis>
      <Min_Inclination>98.390000</Min_Inclination>
      <Max_Inclination>99.010000</Max_Inclination>
      <Min_Eccentricity>0.0</Min_Eccentricity>
      <Max_Eccentricity>0.007</Max_Eccentricity>
    </Tight_Tolerances>
  </Lib_Init>
  <Orbit_Init>
    <Min_Semi_Major_Axis>7186000.000000</Min_Semi_Major_Axis>
    <Nom_Semi_Major_Axis>7195605.347274</Nom_Semi_Major_Axis>
    <Max_Semi_Major_Axis>7209000.000000</Max_Semi_Major_Axis>
    <Min_Inclination>98.690000</Min_Inclination>
    <Nom_Inclination>98.702197</Nom_Inclination>
    <Max_Inclination>98.710000</Max_Inclination>
    <Nom_Eccentricity>0.001141</Nom_Eccentricity>
    <Nom_Arg_Perigee>90.0</Nom_Arg_Perigee>
  </Orbit_Init>
</Data_Block>

```

3.3.3 Schema Reference

An example of validating XML schema for this file type is located at:

http://eop-cfi.esa.int/CFI/EE_CFI_SCHEMAS/EO_OPER_INT_SATCFG_0300.XSD

This schema is compliant to [RD02] and includes format and range checks to ensure compliance to this specification and to the File Format Standard [RD01]. The schema file is named according to section 6.1.1 in [RD02] and is applicable to files named `MMM_OPER_INT_SATCFG_<instance_id>.EOF`.

The following is the content of the [Earth_Observation_File](#) required to reference the above schema.

```

<Earth_Observation_File xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
xsi:schemaLocation="http://eop-cfi.esa.int/CFI http://eop-
cfi.esa.int/CFI/EE_CFI_SCHEMAS/ EO_OPER_INT_SATCFG_0300.XSD"

```



```
schemaVersion="3.0" xmlns="http://eop-cfi.esa.int/CFI">
```

3.4 Attitude Quaternion File

3.4.1 Variable Header

The Variable Header is empty for this type of file.

3.4.2 Data Block

The Attitude quaternion file contains a list of quaternion sets and associated times. Each quaternion set represent the transformation between a given Reference Frame to a given Satellite Based frame. The Data Block content is a sequence of XML elements described in Table 20.

| XML Tag name | Type | Attributes | C Format | Description |
|--------------------|-------------|------------|----------|--|
| Attitude_File_Type | string | - | %s | It defines the Satellite Based Frame. It can be one of the following values: Sat_Nominal_Attitude Sat_Attitude Instr_Attitude |
| Attitude_Data_Type | string | - | %s | It defines the type of attitude data. It can be only the following value: Quaternions |
| Max_Gap | real | unit="s" | %.6f | Maximum gap between two consecutive set of quaternions |
| Quaternions_Data | XML element | - | - | See Table 21. |

Table 20 – Data Block content

| XML Tag name | Type | Attributes | C Format | Description |
|---------------------|-------------|--|----------|--|
| Reference_Frame | string | - | %s | Reference frame. It could be one of the following: BM2000 HM2000 GM2000 MEAN_DATE TRUE_DATE QUASI_MEAN_DATE PSEUDO_TRUE_DATE EARTH_FIXED |
| List_of_Quaternions | XML element | count="N" where n is the number of elements in the list | - | List of Quaternions elements (see Table 22). |

Table 21 – Quaternions_Data element content

| XML Tag name | Type | Attributes | C Format | Description |
|--------------|--------|--|----------|--|
| Time | string | ref="RRR" where RRR is one of the following: TAI UTC UT1 GPS | %s | Date for the quaternions. The date format is CCSDS-A with reference and microseconds (RRR=yyyy-mm-ddThh:nn:ss.ssssss) |
| Q1 | real | - | %.9lf | First coordinate of quaternion vector. Adimensional number with precision of 1e-9 |
| Q2 | real | - | %.9lf | Second coordinate of quaternion vector. Adimensional number with precision of 1e-9 |
| Q3 | real | - | %.9lf | Third coordinate of quaternion vector. Adimensional number with precision of 1e-9 |
| Q4 | real | - | %.9lf | Scalar part of quaternion. Adimensional number with precision of 1e-9 |

Table 22 – Quaternions element content

Example (only first and last item are shown):

```

<Data_Block type="xml">
  <Attitude_File_Type>Sat_Attitude</Attitude_File_Type>
  <Attitude_Data_Type>Quaternions</Attitude_Data_Type>
  <Max_Gap unit="s">11.000000</Max_Gap>
  <Quaternion_Data>
    <Reference_Frame>GM2000</Reference_Frame>
    <List_of_Quaternions count="1442">
      <Quaternions>
        <Time ref="UTC">UTC=2020-04-01T04:00:00.000000</Time>
        <Q1>0.487124882</Q1>
        <Q2>0.165975309</Q2>
        <Q3>0.579456084</Q3>
        <Q4>0.631974836</Q4>
      </Quaternions>
      [...]
      <Quaternions>
        <Time ref="UTC">UTC=2020-04-01T08:00:10.000000</Time>
        <Q1>0.690492661</Q1>
        <Q2>0.408245532</Q2>
        <Q3>0.468027160</Q3>
        <Q4>0.370818080</Q4>
      </Quaternions>
    </List_of_Quaternions>
  </Quaternion_Data>
</Data_Block>

```

3.4.3 Schema Reference

An example of validating XML schema for this file type is located at:



http://eop-cfi.esa.int/CFI/EE_CFI_SCHEMAS/EO_OPER_INT_ATTREF_0300.XSD

This schema is compliant to [RD02] and includes format and range checks to ensure compliance to this specification and to the File Format Standard [RD01]. The schema file is named according to section 6.1.1 in [RD02] and is applicable to files named `MMM_OPER_INT_ATTREF_<instance_id>.EOF`.

The following is the content of the [Earth_Observation_File](#) required to reference the above schema.

```
<Earth_Observation_File xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
xsi:schemaLocation="http://eop-cfi.esa.int/CFI http://eop-
cfi.esa.int/CFI/EE_CFI_SCHEMAS/EO_OPER_INT_ATTREF_0301.XSD"
schemaVersion="3.1" xmlns="http://eop-cfi.esa.int/CFI">
```

3.5 Attitude Roll Pitch Yaw File

3.5.1 Variable Header

The Variable Header is empty for this type of file.

3.5.2 Data Block

The Attitude Roll Pitch Yaw file contains a list of Roll Pitch Yaw sets and associated times. Each set represent the transformation between one reference Satellite Based Frame to another one. The Data Block content is a sequence of XML elements described in Table 23.

| XML Tag name | Type | Attributes | C Format | Description |
|----------------------|-------------|------------|----------|--|
| Attitude_File_Type | string | - | %s | It defines the reference Satellite Based Frame. It can be one of the following values: Sat_Nominal_Attitude Sat_Attitude Instr_Attitude |
| Attitude_Data_Type | string | - | %s | It defines the type of attitude data. It can be only the following value: Attitude_Angles |
| Max_Gap | real | unit="s" | %.6f | Maximum gap between two consecutive set of quaternions |
| Attitude_Angles_Data | XML element | - | - | See Table 24. |

Table 23 – Data Block content

| XML Tag name | Type | Attributes | C Format | Description |
|-------------------------|-------------|--|----------|---|
| Reference_Frame | string | - | %s | Reference frame. It could be one of the following: BM2000 HM2000 GM2000 MEAN_DATE TRUE_DATE QUASI_MEAN_DATE PSEUDO_TRUE_DATE EARTH_FIXED SATELLITE_ACTUAL SATELLITE SATELLITE_RELATIVE |
| List_of_Attitude_Angles | XML element | count="N" where n is the number of elements in the list | - | List of Attitude_Angles elements (see Table 25). |

Table 24 – Attitude_Angles_Data element content

| XML Tag name | Type | Attributes | C Format | Description |
|--------------|--------|---|----------|---|
| Time | string | ref="RRR" where RRR is one of the following: TAI UTC | %s | Date for the quaternions. The date format is CCSDS-A with reference and microseconds (RRR=yyyy-mm-ddThh:nn:ss.sssss) |

| | | UT1 GPS | | |
|-------|------|------------|------|--|
| Pitch | real | unit="deg" | %.6f | Pitch angle in degrees with a precision of 1e-6. |
| Roll | real | unit="deg" | %.6f | Roll angle in degrees with a precision of 1e-6. |
| Yaw | real | unit="deg" | %.6f | Yaw angle in degrees with a precision of 1e-6. |

Table 25 – Attitude_Angles element content

Example (only first and last items are shown):

```
<Data_Block type="xml">
  <Attitude_File_Type>Sat_Attitude</Attitude_File_Type>
  <Attitude_Data_Type>Attitude_Angles</Attitude_Data_Type>
  <Max_Gap unit="s">11.000000</Max_Gap>
  <Attitude_Angles_Data>
    <Reference_Frame>GM2000</Reference_Frame>
    <List_of_Attitude_Angles count="1442">
      <Attitude_Angles>
        <Time ref="UTC">UTC=2020-04-01T04:00:00.000000</Time>
        <Pitch unit="deg">0.000001</Pitch>
        <Roll unit="deg">0.000002</Roll>
        <Yaw unit="deg">0.000003</Yaw>
      </Attitude_Angles>
    [... ]
      <Attitude_Angles>
        <Time ref="UTC">UTC=2020-04-01T08:00:10.000000</Time>
        <Pitch unit="deg">0.000004</Pitch>
        <Roll unit="deg">0.000005</Roll>
        <Yaw unit="deg">0.000006</Yaw>
      </Attitude_Angles>
    </List_of_Attitude_Angles>
  </Attitude_Angles_Data>
</Data_Block>
```

3.5.3 Schema Reference

An example of validating XML schema for this file type is located at:
http://eop-cfi.esa.int/CFI/EE_CFI_SCHEMAS/EO_OPER_INT_ATTREF_0301.XSD

This schema is compliant to [RD02] and includes format and range checks to ensure compliance to this specification and to the File Format Standard [RD01]. The schema file is named according to section 6.1.1 in [RD02] and is applicable to files named `MMM_OPER_INT_ATTREF_<instance_id>.EOF`.

The following is the content of the [Earth_Observation_File](#) required to reference the above schema.

```
<Earth_Observation_File xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
  xsi:schemaLocation="http://eop-cfi.esa.int/CFI http://eop-
  cfi.esa.int/CFI/EE_CFI_SCHEMAS/EO_OPER_INT_ATTREF_0301.XSD"
  schemaVersion="3.1" xmlns="http://eop-cfi.esa.int/CFI">
```


3.6 Swath Definition File

3.6.1 Variable Header

The Variable Header is empty for this type of file.

3.6.2 Data Block

The Data Block content is a sequence of XML elements described in Table 26.

| XML Tag name | Type | Attributes | C Format | Description |
|--------------|-------------|------------|----------|------------------------------------|
| Swath | XML element | - | - | Swath data structure see Table 27. |

Table 26 – Data Block content

| XML Tag name | Type | Attributes | C Format | Description |
|---|-------------|--|----------|--|
| Output_File_Description | string | - | %s | File Description for the output swath template file |
| Output_File_Type | string | - | %s | File type for the output swath template file. It should have the fixed value “MPL SWTREF” |
| Swath_Type | string | - | %s | Swath type. It can have one of the following values: <ul style="list-style-type: none"> • point • line • inertial |
| Num_Swath_Records | integer | - | %d | Number of points in the swath template file (>0) |
| Refraction | XML element | - | - | Refraction model structure, see Table 28 |
| Either List_of_Swath_Points or Asar_Geometry | XML element | List_of_Swath_Points count=”n” number of points in the instantaneous swath Asar_Geometry No attributes | - | List_of_Swath_Points: List of Swath_Point elements. Each element contains the geometry data for the calculation of each point in the instantaneous swath. See Table 29 Asar_Geometry: ASAR geometry, see Table 29 |
| Sat_Nominal_Att | XML element | - | - | Satellite Nominal Attitude initialization data, see Table 38. |
| Sat_Att | XML element | - | - | Satellite Attitude initialization data, see Table 39. |
| Instr_Att | XML element | - | - | Instrument Attitude initialization data, see Table 39. |

Table 27 – Swath element content

| XML Tag name | Type | Attributes | C Format | Description |
|--------------|--------|------------|----------|---|
| Model | string | - | %s | Atmospheric refraction model. It can be one of: <ul style="list-style-type: none"> • NO_REF • STD_REF • USER_REF • PRED_REF |
| Freq | real | unit=”MHz” | %lf | Signal Frequency in MHz (≥ 0) |

Table 28 – Refraction element content

| XML Tag name | Type | Attributes | C Format | Description |
|---|----------------|------------|----------|--|
| One of the following Pointing_Geometry Distance_Geometry Limb_Geometry Inertial_Geometry Sub_Satellite_Geometry Asar_Geometry Incidence_Angle_Geometry | XML element | - | %s | It Contains the geometry data for the calculation of each point in the instantaneous swath. Pointing_Geometry: see Table 30 Distance_Geometry: see Table 32 Limb_Geometry: see Table 31 Inertial_Geometry: see Table 31 Sub_Satellite_Geometry: see Table 36 Asar_Geometry: see Table 33 Incidence_Angle_Geometry: see Table 37 |

Table 29 – Swath_Point element content

| XML Tag name | Type | Attributes | C Format | Description |
|--------------|------|------------|----------|---------------------------------|
| Azimuth | real | unit="deg" | %lf | Swath azimuth in deg [0,360) |
| Elevation | real | unit="deg" | %lf | Swath elevation in deg [-90,90] |
| Altitude | real | unit="m" | %lf | Swath altitude in m (>= 0) |

Table 30 – Pointing_Geometry element content

| XML Tag name | Type | Attributes | C Format | Description |
|--------------|------|------------|----------|------------------------------|
| Azimuth | real | unit="deg" | %lf | Swath azimuth in deg [0,360) |
| Altitude | real | unit="m" | %lf | Swath altitude in m (>= 0) |

Table 31 – Limb_ and Inertial_Geometry element content

| XML Tag name | Type | Attributes | C Format | Description |
|--------------|------|------------|----------|---------------------------------|
| Azimuth | real | unit="deg" | %lf | Swath azimuth in deg [0,360) |
| Elevation | real | unit="deg" | %lf | Swath elevation in deg [-90,90] |
| Altitude | real | unit="m" | %lf | Swath altitude in m (>= 0) |
| Distance | real | unit="m" | %lf | distance in m (>= 0) |

Table 32 – Distance_Geometry element content

| XML Tag name | Type | Attributes | C Format | Description |
|--|----------------|------------|----------|---|
| Left_Pt | XML element | - | - | It Contains the geometry data for the calculation of the left point in the instantaneous swath. It has the same content of Pointing_Geometry: see Table 30 |
| Mid_Pt | XML element | - | - | It Contains the geometry data for the calculation of the mid point in the instantaneous swath. It has the same content of Pointing_Geometry: see Table 30 |
| Right_Pt | XML element | - | - | It Contains the geometry data for the calculation of the right point in the instantaneous swath. It has the same content of Pointing_Geometry: see Table 30 |
| Either Narrow_Asar Or Wide_Asar | XML element | - | - | Slant range extension parameters. Narrow_Asar: see Table 34 Wide_Asar: see Table 35 |

| | | | | |
|--|--|--|--|--|
| | | | | |
|--|--|--|--|--|

Table 33 – Asar_Geometry element content

| XML Tag name | Type | Attributes | C Format | Description |
|------------------|------|---------------|----------|---|
| Slant_Range_Left | real | unit="10e-6s" | %lf | Slant Range Extension parameter for left point in microseconds. |

Table 34 – Narrow_Asar element content

| XML Tag name | Type | Attributes | C Format | Description |
|-------------------|------|---------------|----------|--|
| Slant_Range_Left | real | unit="10e-6s" | %lf | Slant Range Extension parameter for left point in microseconds. |
| Slant_Range_Right | real | unit="10e-6s" | %lf | Slant Range Extension parameter for right point in microseconds. |

Table 35 – Wide_Asar element content

| XML Tag name | Type | Attributes | C Format | Description |
|--------------|------|------------|----------|------------------------------|
| Azimuth | real | unit="deg" | %lf | Swath azimuth in deg [0,360) |

Table 36 – Sub_Satellite_Geometry element content

| XML Tag name | Type | Attributes | C Format | Description |
|-----------------|------|------------|----------|-------------------------------------|
| Azimuth | real | unit="deg" | %lf | Swath azimuth in deg [0,360) |
| Incidence_Angle | real | unit="deg" | %lf | Swath incidence angle in deg [0,90) |
| Altitude | real | unit="m" | %lf | Swath altitude in m (>= 0) |

Table 37 – Incidence_Angle_Geometry element content

| XML Tag name | Type | Attributes | C Format | Description |
|--|---|------------|-------------------|--|
| One of the following None AOCS_Model Parameter_Model Harmonic_Model File_Model XML element | AOCS_Model integer Parameter_Model Harmonic_Model File_Model XML element None XML element (empty) | - | AOCS_Model %ld | Satellite Nominal Attitude initialization data AOCS_Model One of the following values 0: Geocentric Pointing 1: Local Normal Pointing 2: Yaw Steering 3: Zero Doppler Parameter_Model: see Table 40 Harmonic_Model: see Table 41 File_Model: see Table 42 |

Table 38 – Sat_Nominal_Att element content

| XML Tag name | Type | Attributes | C Format | Description |
|---|---|------------|----------|---|
| One of the following None Angle_Model Matrix_Model Harmonic_Model File_Model | XML element None XML element (empty) | - | - | Satellite Attitude initialization data Angle_Model: see Table 43 Matrix_Model: see Table 44 Harmonic_Model: see Table 41 File_Model: see Table 42 |

Table 39 – Sat_ and Instrument_Att element content

| XML Tag name | Type | Attributes | C Format | Description |
|--------------|------|------------|----------|-------------|
|--------------|------|------------|----------|-------------|

| | | | | |
|--------------------|-------------|---|-----|---|
| Model | integer | - | %ld | Attitude Model Identifier |
| List_of_Parameters | XML element | count="n" where n is the number of elements in the list | - | List of Parameter elements. See Table 45. |

Table 40 – Parameter_Model element content

| XML Tag name | Type | Attributes | C Format | Description |
|--|-------------|---|----------|--|
| Angle_Type | integer | - | %ld | Angle Type |
| List_of_Harmonic_Pitch | XML element | count="n" where n is the number of elements in the list | - | List of Harmonic elements for Pitch, see Table 46. |
| List_of_Harmonic_Roll | XML element | count="n" where n is the number of elements in the list | - | List of Harmonic elements for Roll see Table 46. |
| List_of_Harmonic_Yaw | XML element | count="n" where n is the number of elements in the list | - | List of Harmonic elements for Yaw see Table 46. |
| Offsets (present only in Instr_Att) | XML element | - | - | See Table 47. |

Table 41 – Harmonic_Model element content

| XML Tag name | Type | Attributes | C Format | Description |
|---|-------------|---|----------|--|
| List_of_Files | XML element | count="n" where n is the number of elements in the list | %ld | List of File elements, see Table 48. |
| Auxiliary_File (present only in Sat_Att) | string | - | %s | Attitude auxiliary file name |
| Time_Selection | XML element | - | - | It indicates the time window to be read from the attitude files. See Table 49. |

Table 42 – File_Model element content

| XML Tag name | Type | Attributes | C Format | Description |
|--|-------------|------------|----------|-------------------------|
| Angle_1 | real | unit="deg" | %lf | Pitch Mispointing Angle |
| Angle_2 | real | unit="deg" | %lf | Roll Mispointing Angle |
| Angle_3 | real | unit="deg" | %lf | Yaw Mispointing Angle |
| Offsets (present only in Instr_Att) | XML element | - | - | See Table 47. |

Table 43 – Angle_Model element content

| XML Tag name | Type | Attributes | C Format | Description |
|--|-------------|------------|----------|-------------------------------|
| Row_1 | real | unit="deg" | %lf | Mispointing matrix first row |
| Row_2 | real | unit="deg" | %lf | Mispointing matrix second row |
| Row_3 | real | unit="deg" | %lf | Mispointing matrix third row |
| Offsets (present only in Instr_Att) | XML element | - | - | See Table 47. |

Table 44 – Matrix_Model element content

| XML Tag name | Type | Attributes | C Format | Description |
|--------------|--------|------------|----------|-------------|
| Parameter | string | - | %s | Parameter |

Table 45 – Parameter element content



| XML Tag name | Type | Attributes | C Format | Description |
|----------------------|---------|------------|----------|----------------------|
| Harmonic_Type | integer | - | %ld | Harmonic Type |
| Harmonic_Coefficient | real | - | %lf | Harmonic Coefficient |

Table 46 – Harmonic element content

| XML Tag name | Type | Attributes | C Format | Description |
|--------------|------|------------|----------|-------------|
| Offset_X | real | unit="m" | %lf | X offset |
| Offset_Y | real | unit="m" | %lf | Y offset |
| Offset_Z | real | unit="m" | %lf | Z offset |

Table 47 – Offsets element content

| XML Tag name | Type | Attributes | C Format | Description |
|--------------|--------|------------|----------|-------------------------------|
| File | string | - | %s | Attitude filename (full path) |

Table 48 – File element content

| XML Tag name | Type | Attributes | C Format | Description |
|--|----------------|---|----------|--|
| Either Select_File Or Time_Window | XML element | Time_Window time_ref="REF" being REF one of the following: UTC UT1 TAI GPS | - | Select_File: the whole files to be read (the tag has an empty value) Time_Window: indicates which part of the files has to be read. See Table 50. |

Table 49 – Time_Selection element content

| XML Tag name | Type | Attributes | C Format | Description |
|--------------|------|------------|----------|-----------------------|
| Time_0 | real | - | %lf | Start time in MJD2000 |
| Time_1 | real | - | %lf | Stop time in MJD2000 |

Table 50 – Time_Window element content

| XML Tag name | Type | Attributes | C Format | Description |
|--------------|------|------------|----------|------------------------------|
| Column_1 | real | - | %lf | Element in the first column |
| Column_2 | real | - | %lf | Element in the second column |
| Column_3 | real | - | %lf | Element in the third column |

Table 51 – Row element content

Example:

```
<Data_Block type="xml">
  <Swath>
    <Output_File_Description>OLCI</Output_File_Description>
    <Output_File_Type>MPL_SWTREF</Output_File_Type>
    <Swath_Type>open</Swath_Type>
    <Num_Swath_Records>1200</Num_Swath_Records>
    <Refraction>
      <Model>NO_REF</Model>
      <Freq unit="MHz">0.0</Freq>
    </Refraction>
    <List_of_Swath_Points count="3">
      <Swath_Point>
        <Pointing_Geometry>
          <Azimuth unit="deg">+270.000000</Azimuth>
          <Elevation unit="deg">+068.295000</Elevation>
          <Altitude unit="m">+000000.000</Altitude>
        </Pointing_Geometry>
      </Swath_Point>
    </List_of_Swath_Points>
  </Swath>
</Data_Block>
```



```

    <Swath_Point>
      <Pointing_Geometry>
        <Azimuth unit="deg">+090.000000</Azimuth>
        <Elevation unit="deg">+090.000000</Elevation>
        <Altitude unit="m">+000000.000</Altitude>
      </Pointing_Geometry>
    </Swath_Point>
    <Swath_Point>
      <Pointing_Geometry>
        <Azimuth unit="deg">+090.000000</Azimuth>
        <Elevation unit="deg">+043.135000</Elevation>
        <Altitude unit="m">+000000.000</Altitude>
      </Pointing_Geometry>
    </Swath_Point>
  </List_of_Swath_Points>
  <Sat_Nominal_Att>
    <AOCs_Model>2</AOCs_Model>
  </Sat_Nominal_Att>
  <Sat_Att>
    <None></None>
  </Sat_Att>
  <Instr_Att>
    <None></None>
  </Instr_Att>
</Swath>
</Data_Block>

```

3.6.3 Schema Reference

An example of validating XML schema for this file type is located at:
http://eop-cfi.esa.int/CFI/EE_CFI_SCHEMAS/EO_OPER_MPL_SW_DEF_0400.XSD

This schema is compliant to [RD02] and includes format and range checks to ensure compliance to this specification and to the File Format Standard [RD01]. The schema file is named according to section 6.1.1 in [RD02] and is applicable to files named `MMM_OPER_MPL_SW_DEF_<instance_id>.EOF`.

The following is the content of the [Earth_Observation_File](#) required to reference the above schema.

```

<Earth_Observation_File xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
  xsi:schemaLocation="http://eop-cfi.esa.int/CFI http://eop-
cfi.esa.int/CFI/EE_CFI_SCHEMAS/EO_OPER_MPL_SW_DEF_0401.XSD"
  xmlns="http://eop-cfi.esa.int/CFI" schemaVersion="4.1">

```

3.7 Swath Template File

3.7.1 Variable Header

The Variable Header content is a sequence of XML elements described in Table 52.

| XML Tag name | Type | Attributes | C Format | Description |
|---|---|--|----------|--|
| Reference_OSF | string | - | %s | Orbit Scenario File used for generating the file |
| Reference_SDF | string | - | %s | Swath definition file used for generating the file |
| Absolute_Orbit | integer | - | %ld | Orbit for which the STF has been generated |
| Start_Validity_Orbit | integer | - | %ld | First orbit for which the STF is valid |
| Stop_Validity_Orbit | integer | - | %ld | Last orbit for which the STF is valid |
| Swath_Type | string. one of the following values: • open • closed | - | %s | Swath type |
| Swath_Point_Type | string. one of the following values: • geodetic • inertial | - | %s | Describes the type of swath points: inertial (RA and Declination) or geodetic (longitude and latitude) |
| One of the following: Orbit_Geometry Orbit_State_Vector | XML element | - | - | Orbit_Geometry: see Table 54. Orbit_State_Vector: see Table 55. |
| Time_Step | real | unit="s" | %f | Seconds between two swath points |
| List_of_STF_Altitudes | XML element | count="n" where n is the number of elements in the list | - | List of STF_Altitude elements, see Table 53 |
| Refraction | XML element | - | - | Refraction model structure, see Table 28 |

Table 52 – Variable Header content

| XML Tag name | Type | Attributes | C Format | Description |
|--------------|------|------------|----------|---------------------------------|
| STF_Altitude | real | unit="m" | %f | Altitude for a swath point in m |

Table 53 – STF_Altitude element content

| XML Tag name | Type | Attributes | C Format | Description |
|--------------|------|--------------|----------|-----------------------------|
| Repeat_Cycle | real | unit="day" | %f | Repeat cycle in days |
| Cycle_Length | real | unit="orbit" | %f | Cycle length in orbits |
| MLST_Drift | real | unit="s/day" | %f | Mean local solar time drift |

Table 54 – Orbit_Geometry element content

| XML Tag name | Type | Attributes | C Format | Description |
|----------------|---------|------------|----------|---|
| Absolute_Orbit | integer | - | %d | Orbit number for the swath template file. |
| Pos_X | real | unit="m" | %f | Position in X coordinate (meters) |
| Pos_Y | real | unit="m" | %f | Position in Y coordinate (meters) |

| | | | | |
|-------|------|------------|----|-----------------------------------|
| Pos_Z | real | unit="m" | %f | Position in Z coordinate (meters) |
| Vel_X | real | unit="m/s" | %f | Velocity in X coordinate (m/s) |
| Vel_Y | real | unit="m/s" | %f | Velocity in Y coordinate (m/s) |
| Vel_Z | real | unit="m/s" | %f | Velocity in Z coordinate (m/s) |

Table 55 – Orbit_State_Vector element content

Example:

```

<Variable_Header>

<Reference_OSF>MMM_OPER_MPL_ORBSCT_20200401T040000_20200401T080010_0001.EOF</
Reference_OSF>

<Reference_SDF>MMM_OPER_MPL_SW_DEF_20200101T000000_20300101T000000_0001.EOF</
Reference_SDF>
  <Absolute_Orbit>2000</Absolute_Orbit>
  <Start_Validity_Orbit>1990</Start_Validity_Orbit>
  <Stop_Validity_Orbit>2010</Stop_Validity_Orbit>
  <Swath_Type>open</Swath_Type>
  <Swath_Point_Type>geodetic</Swath_Point_Type>
  <Orbit_Geometry>
    <Repeat_Cycle unit="day">35</Repeat_Cycle>
    <Cycle_Length unit="orbit">501</Cycle_Length>
    <MLST_Drift unit="s/day">+000.000000</MLST_Drift>
  </Orbit_Geometry>
  <Time_Step unit="s">5.029940120</Time_Step>
  <List_of_STF_Alitudes count="4">
    <STF_Alitude unit="m">+000000.000</STF_Alitude>
    <STF_Alitude unit="m">+000000.000</STF_Alitude>
    <STF_Alitude unit="m">+000000.000</STF_Alitude>
    <STF_Alitude unit="m">+000000.000</STF_Alitude>
  </List_of_STF_Alitudes>
  <Refraction>
    <Model>NO_REF</Model>
    <Freq unit="MHz">0.0</Freq>
  </Refraction>
</Variable_Header>

```

3.7.2 Data Block

The Data Block content is a sequence of XML elements described in Table 56.

| XML Tag name | Type | Attributes | C Format | Description |
|-----------------|-------------|--|----------|--|
| List_of_STF_Pts | XML element | count="n" where n is the number of elements in the list | - | List of STF_Pt elements, see Table 57. |

Table 56 – Data Block content

| XML Tag name | Type | Attributes | C Format | Description |
|--|-------------|--|----------|--|
| One of the following List_of_Geodetic_Pts List_of_Inertial_Pts | XML element | count="n" where n is the number of elements in the list | - | List_of_Geodetic_Pts: List of Geodetic_Pt elements, see Table 58. List_of_Inertial_Pts: List of Inertial_Pt elements, see Table 59. |



Table 57 – STF_Pt element content

| XML Tag name | Type | Attributes | C Format | Description |
|--------------|------|------------|----------|-------------------------------|
| Long | real | unit="deg" | %f | Longitude of the point in deg |
| Lat | real | unit="deg" | %f | Latitude of the point in deg |

Table 58 – Geodetic_Pt element content

| XML Tag name | Type | Attributes | C Format | Description |
|--------------|------|------------|----------|------------------------|
| Ra | real | unit="deg" | %f | Right Ascension in deg |
| Dec | real | unit="deg" | %f | Declination in deg |

Table 59 – Inertial_Pt element content

Example (only few points are shown):

```
<Data_Block type="xml">
  <List_of_STF_Pts count="1200">
    <STF_Pt>
      <List_of_Geodetic_Pts count="4">
        <Geodetic_Pt>
          <Long unit="deg">-000.000000</Long>
          <Lat unit="deg">-000.000000</Lat>
        </Geodetic_Pt>
        <Geodetic_Pt>
          <Long unit="deg">-000.000000</Long>
          <Lat unit="deg">-010.000000</Lat>
        </Geodetic_Pt>
        <Geodetic_Pt>
          <Long unit="deg">-010.000000</Long>
          <Lat unit="deg">-010.000000</Lat>
        </Geodetic_Pt>
        <Geodetic_Pt>
          <Long unit="deg">-010.000000</Long>
          <Lat unit="deg">-000.000000</Lat>
        </Geodetic_Pt>
      </List_of_Geodetic_Pts count="4">
    </STF_Pt>
```

[...]

```
<STF_Pt>
  <List_of_Geodetic_Pts count="4">
    <Geodetic_Pt>
      <Long unit="deg">010.000000</Long>
      <Lat unit="deg">350.000000</Lat>
    </Geodetic_Pt>
    <Geodetic_Pt>
      <Long unit="deg">010.000000</Long>
      <Lat unit="deg">000.000000</Lat>
    </Geodetic_Pt>
    <Geodetic_Pt>
      <Long unit="deg">020.000000</Long>
      <Lat unit="deg">-010.000000</Lat>
    </Geodetic_Pt>
    <Geodetic_Pt>
      <Long unit="deg">020.000000</Long>
      <Lat unit="deg">350.000000</Lat>
```



```
        </Geodetic_Pt>
      </List_of_Geodetic_Pts>
    </STF_Pt>
  </List_of_STF_Pts>
</Data_Block>
```

3.7.3 Schema Reference

An example of validating XML schema for this file type is located at:
http://eop-cfi.esa.int/CFI/EE_CFI_SCHEMAS/EO_OPER_MPL_SWTREF_0400.XSD

This schema is compliant to [RD02] and includes format and range checks to ensure compliance to this specification and to the File Format Standard [RD01]. The schema file is named according to section 6.1.1 in [RD02] and is applicable to files named `MMM_OPER_MPL_SWTREF_<instance_id>.EOF`.

The following is the content of the [Earth_Observation_File](#) required to reference the above schema.

```
<Earth_Observation_File xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
  xsi:schemaLocation="http://eop-cfi.esa.int/CFI http://eop-
cfi.esa.int/CFI/EE_CFI_SCHEMAS/EO_OPER_MPL_SWTREF_0400.XSD"
  xmlns="http://eop-cfi.esa.int/CFI" schemaVersion="4.0">
```

3.8 Zone Database File

3.8.1 Variable Header

The Variable Header is empty for this type of file.

3.8.2 Data Block

The Data Block content is a sequence of XML elements described in Table 60.

| XML Tag name | Type | Attributes | C Format | Description |
|---------------|-------------|---|----------|-------------------------------------|
| List_of_Zones | XML element | count="n" where n is the number of elements in the list | - | List of Zone elements. See Table 61 |

Table 60 – Data Block content

| XML Tag name | Type | Attributes | C Format | Description |
|---------------------|-------------|---|----------|--|
| Zone_Id | string | - | %s | Zone name |
| Zone_Description | string | - | %s | Zone description |
| Surface | string | - | %s | Type of surface |
| Projection | string | - | %s | Projection |
| Creator | string | - | %s | Creator name |
| List_of_Polygon_Pts | XML element | count="n" where n is the number of elements in the list | - | List of Polygon_Pt elements, points defining the zone. See Table 62. |
| Diameter | real | unit="m" | %f | Diameter of the zone if the list of polygon points is empty. |

Table 61 – Zone element content

| XML Tag name | Type | Attributes | C Format | Description |
|--------------|------|------------|----------|---|
| Long | real | unit="deg" | %f | longitude of the point in deg (-360, 360) |
| Lat | real | unit="deg" | %f | latitude of the point in deg (-90, 90) |

Table 62 – Polygon_Pt element content



Example:

```
<Data_Block type="xml">
  <List_of_Zones count="1">
    <Zone>
      <Zone_Id>RECT_ZONE</Zone_Id>
      <Zone_Description></Zone_Description>
      <Surface></Surface>
      <Projection>RECTANGULAR</Projection>
      <Creator>TEST DATA</Creator>
      <List_of_Polygon_Pts count="4">
        <Polygon_Pt>
          <Long unit="deg">-030.000000</Long>
          <Lat unit="deg">-020.000000</Lat>
        </Polygon_Pt>
        <Polygon_Pt>
          <Long unit="deg">-030.000000</Long>
          <Lat unit="deg">-010.000000</Lat>
        </Polygon_Pt>
        <Polygon_Pt>
          <Long unit="deg">-011.000000</Long>
          <Lat unit="deg">-010.000000</Lat>
        </Polygon_Pt>
        <Polygon_Pt>
          <Long unit="deg">-011.000000</Long>
          <Lat unit="deg">-020.000000</Lat>
        </Polygon_Pt>
      </List_of_Polygon_Pts>
      <Diameter unit="m">+000.000000</Diameter>
    </Zone>
  </List_of_Zones>
</Data_Block>
```

3.8.3 Schema Reference

An example of validating XML schema for this file type is located at:

http://eop-cfi.esa.int/CFI/EE_CFI_SCHEMAS/EO_OPER_MPL_ZON_DB_0300.XSD

This schema is compliant to [RD02] and includes format and range checks to ensure compliance to this specification and to the File Format Standard [RD01]. The schema file is named according to section 6.1.1 in [RD02] and is applicable to files named `MMM_OPER_MPL_ZON_DB_<instance_id>.EOF`.

The following is the content of the [Earth_Observation_File](#) required to reference the above schema.

```
<Earth_Observation_File
  xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
  xsi:schemaLocation="http://eop-cfi.esa.int/CFI http://eop-
cfi.esa.int/CFI/EE_CFI_SCHEMAS/EO_OPER_MPL_ZON_DB_0300.XSD"
  xmlns="http://eop-cfi.esa.int/CFI" schemaVersion="3.0">
```

3.9 Station Database File

3.9.1 Variable Header

The Variable Header is empty for this type of file.

3.9.2 Data Block

The Data Block content is a sequence of XML elements described in Table 63.

| XML Tag name | Type | Attributes | C Format | Description |
|------------------------|-------------|---|----------|---|
| List_of_Ground_Station | XML element | count="n" where n is the number of elements in the list | - | List of Ground_Station elements. See Table 61 |

Table 63 – Data Block content

| XML Tag name | Type | Attributes | C Format | Description |
|----------------------|-------------|---|----------|---|
| Station_Id | string | - | %s | Station name |
| Descriptor | string | - | %s | Station description |
| Antenna | string | - | %s | Antenna band |
| Frequency (optional) | real | unit="Hz" | %f | Frequency in Hz |
| Purpose | string | - | %s | Purpose |
| Type | string | - | %s | Station Type |
| Location | XML element | - | - | Station location. See Location element, Table 65. |
| List_of_Spacecrafts | XML element | count="n" where n is the number of elements in the list | - | Spacecraft dependant mask type parameters. List of Spacecraft elements, see Table 66. |
| Default_El | real | unit="deg" | %f | Default elevation in deg. |
| List_of_Mask_Points | XML element | count="n" where n is the number of elements in the list | - | List of Mask_Point elements, see Table 67. |

Table 64 – Ground_Station element content

| XML Tag name | Type | Attributes | C Format | Description |
|--------------|------|------------|----------|------------------|
| Long | real | unit="deg" | %f | Longitude in deg |
| Lat | real | unit="deg" | %f | Latitude in deg |
| Alt | real | unit="deg" | %f | Altitude in deg |

Table 65 – Location element content

| XML Tag name | Type | Attributes | C Format | Description |
|--------------|--------|------------|----------|--|
| Name | string | - | %s | Spacecraft name |
| Aos_El | real | unit="deg" | %f | Acquisition of signal elevation |
| Los_El | real | unit="deg" | %f | Loss of signal elevation |
| Mask | string | - | %s | Mask type. Possible values: AOS_LOS_WITH_MASK AOS_LOS MASK_ONLY |

Table 66 – Spacecraft element content

| XML Tag name | Type | Attributes | C Format | Description |
|--------------|------|------------|----------|-------------|
|--------------|------|------------|----------|-------------|

| | | | | |
|----|------|------------|----|-----------|
| Az | real | unit="deg" | %f | Azimuth |
| El | real | unit="deg" | %f | Elevation |

Table 67 – Mask_Point element content

Example (only few Mask Points are shown):

```

<Data_Block type="xml">
  <List_of_Ground_Stations count="1">
    <Ground_Station>
      <Station_id>GSVLBRHX</Station_id>
      <Descriptor>Svalbard (PLATABERGET)</Descriptor>
      <Antenna>X-BAND </Antenna>
      <Purpose>GLOBAL + REGIONAL </Purpose>
      <Type> </Type>
      <Location>
        <Long unit="deg">+015.400000</Long>
        <Lat unit="deg">+078.130000</Lat>
        <Alt unit="m">+0470.000</Alt>
      </Location>
    </Ground_Station>
  </List_of_Ground_Stations>
  <List_of_Spacecrafts count="1">
    <Spacecraft>
      <Name>SMOS</Name>
      <Aos_El unit="deg">+005.000000</Aos_El>
      <Los_El unit="deg">+005.000000</Los_El>
      <Mask>AOS_LOS_WITH_MASK</Mask>
    </Spacecraft>
  </List_of_Spacecrafts>
  <Default_El unit="deg">+0000.000</Default_El>
  <List_of_Mask_Points count="22">
    <Mask_Point>
      <Az unit="deg">+000.000000</Az>
      <El unit="deg">+000.400000</El>
    </Mask_Point>
    <Mask_Point>
      <Az unit="deg">+032.000000</Az>
      <El unit="deg">+000.400000</El>
    </Mask_Point>
    [...]
    <Mask_Point>
      <Az unit="deg">+272.000000</Az>
      <El unit="deg">+000.400000</El>
    </Mask_Point>
    <Mask_Point>
      <Az unit="deg">+360.000000</Az>
      <El unit="deg">+000.400000</El>
    </Mask_Point>
  </List_of_Mask_Points>
</Ground_Station> >
</List_of_Ground_Stations>
</Data_Block>

```



3.9.3 Schema Reference

An example of validating XML schema for this file type is located at:
http://eop-cfi.esa.int/CFI/EE_CFI_SCHEMAS/EO_OPER_MPL_GND_DB_0300.XSD

This schema is compliant to [RD02] and includes format and range checks to ensure compliance to this specification and to the File Format Standard [RD01]. The schema file is named according to section 6.1.1 in [RD02] and is applicable to files named `MMM_OPER_MPL_GND_DB_<instance_id>.EOF`.

The following is the content of the [Earth_Observation_File](#) required to reference the above schema.

```
<Earth_Observation_File
  xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
  xsi:schemaLocation="http://eop-cfi.esa.int/CFI http://eop-
cfi.esa.int/CFI/EE_CFI_SCHEMAS/EO_OPER_MPL_GND_DB_0300.XSD"
  xmlns="http://eop-cfi.esa.int/CFI" schemaVersion="3.0">
```

3.10 Attitude Definition File

3.10.1 Variable Header

The Variable Header is empty for this type of file.

3.10.2 Data Block

The Data Block content is a sequence of XML elements described in Table 68.

| XML Tag name | Type | Attributes | C Format | Description |
|---------------------|-------------|------------|----------|--|
| Attitude_Definition | XML element | - | - | Attitude_Definition data structure see |

Table 68 – Data Block content

| XML Tag name | Type | Attributes | C Format | Description |
|-----------------|-------------|------------|----------|--|
| Sat_Nominal_Att | XML element | - | - | Satellite Nominal Attitude initialization data, see Table 70 |
| Sat_Att | XML element | - | - | Satellite Attitude initialization data, see Table 71. |
| Instr_Att | XML element | - | - | Instrument Attitude initialization data, see Table 71. |

Table 69 – Swath element content

| XML Tag name | Type | Attributes | C Format | Description |
|--|---|------------|----------------|---|
| One of the following: None AOCS_Model Parameter_Model Harmonic_Model File_Model | AOCS_Model integer Parameter_Model Harmonic_Model File_Model XML element None XML element (empty) | - | AOCS_Model %ld | Satellite Nominal Attitude initialization data AOCS_Model AOCS model. It can contain the name of the AOCS model or the corresponding number, both are allowed. The allowed values are the following (the equivalent number is shown between parenthesis): GEOCENTRIC_POINTING (0) LOCAL_NORMAL_POINTING (1) YAW_STEERING_MODE (2) ZERO_DOPPLER_YSM (3) Parameter_Model: see Table 40 Harmonic_Model: see Table 41 File_Model: see Table 42 |

Table 70 – Sat_Nominal_Att element content

| XML Tag name | Type | Attributes | C Format | Description |
|---|--|------------|----------|---|
| One of the following None Angle_Model Matrix_Model Harmonic_Model File_Model | XML element None XML element | - | - | Satellite Attitude initialization data Angle_Model: see Table 43 Matrix_Model: see Table 44 Harmonic_Model: see Table 41 File_Model: see Table 42 |

| | | | | |
|--|---------|--|--|---|
| Only in Sat_Att Quaternion_Plus_Angle Quaternion_Plus_Matrix | (empty) | | | Quaternion_Plus_Angle Quaternion_Plus_Matrix |
|--|---------|--|--|---|

Table 71 – Sat_ and Instrument_Att element content

| XML Tag name | Type | Attributes | C Format | Description |
|--------------------|-------------|---|----------|---|
| Model | integer | - | %ld | Attitude Model Identifier It can contain the name of the model or the corresponding number, both are allowed. The allowed values are the following (the equivalent number is shown between parenthesis): GENERIC (0) ENVISAT (1) CRYOSAT (2) ADM (3) SENTINEL1 (4) SENTINEL2 (5) GEO (6) METOPSG (7) |
| List_of_Parameters | XML element | count="n" where n is the number of elements in the list | - | List of Parameter elements. See Table 45. |

Table 72 – Parameter_Model element content

| XML Tag name | Type | Attributes | C Format | Description |
|--|-------------|---|----------|--|
| Angle_Type | integer | - | %ld | It can contain the name of the angle type or the corresponding number, both are allowed. The allowed values are the following (the equivalent number is shown between parenthesis): TRUE_LAT_TOD (0) TRUE_LAT_EF (1) |
| List_of_Harmonic_Pitch | XML element | count="n" where n is the number of elements in the list | - | List of Harmonic elements for Pitch see Table 46. |
| List_of_Harmonic_Roll | XML element | count="n" where n is the number of elements in the list | - | List of Harmonic elements for Roll see Table 46. |
| List_of_Harmonic_Yaw | XML element | count="n" where n is the number of elements in the list | - | List of Harmonic elements for Yaw see Table 46. |
| Offsets (present only in Instr_Att) | XML element | - | - | See Table 47. |

Table 73 – Harmonic_Model element content

| XML Tag name | Type | Attributes | C Format | Description |
|-----------------|------------------------------|------------|----------|--|
| Angle_Model | Structure (see Table 249) | - | - | Angles see Table 43 |
| Quaternion_File | string | - | %s | Name of the file containing the list of quaternions. |

Table 74 – Quaternion_Plus_Angle element content

| XML Tag name | Type | Attributes | C Format | Description |
|-----------------|---------------------------|------------|----------|--|
| Matrix_Model | Structure (see Table 250) | - | - | Matrix see Table 44 |
| Quaternion_File | string | - | %s | Name of file containing the list of quaternions. |

Table 75 – Quaternion_Plus_Matrix element content

Example:

```

<Data_Block type="xml">
  <Attitude_Definition>

    <Sat_Nominal_Att>
      <AOCS_Model>YAW_STEERING_MODE</AOCS_Model>
    </Sat_Nominal_Att>

    <Sat_Att>
      <File_Model>
        <List_of_Files count="1">

<File>MA1_TEST_AUX_ATTRES_20210408T050853_20210408T101753_0001.EOF</File>
          </List_of_Files>
        <Auxiliary_File/>
        <Time_Selection>
          <Select_File/>
        </Time_Selection>
      </File_Model>
    </Sat_Att>

    <Instr_Att>
      <Angle_Model>
        <Angle_1 unit="deg">0.0</Angle_1>
        <Angle_2 unit="deg">0.0</Angle_2>
        <Angle_3 unit="deg">0.0</Angle_3>
        <Offset_X unit="m">0.0</Offset_X>
        <Offset_Y unit="m">0.0</Offset_Y>
        <Offset_Z unit="m">0.0</Offset_Z>
      </Angle_Model>
    </Instr_Att>

  </Attitude_Definition>
</Data_Block>

```

3.10.3 Schema Reference

An example of validating XML schema for this file type is located at:
http://eop-cfi.esa.int/CFI/EE_CFI_SCHEMAS/EO_OPER_INT_ATTDEF_0302.XSD

This schema is compliant to [RD02] and includes format and range checks to ensure compliance to this specification and to the File Format Standard [RD01]. The schema file is named according to section 6.1.1 in [RD02] and is applicable to files named `MMM_OPER_INT_ATTDEF_<instance_id>.EOF`.

The following is the content of the [Earth_Observation_File](#) required to reference the above schema.



```
<Earth_Observation_File
  xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
  xsi:schemaLocation="http://eop-cfi.esa.int/CFI http://eop-
cfi.esa.int/CFI/EE_CFI_SCHEMAS/EO_OPER_INT_ATTDEF_0302.XSD"
  xmlns="http://eop-cfi.esa.int/CFI" schemaVersion="3.2">
```

3.11 Field of View Configuration File

3.11.1 Variable Header

The Variable Header is empty for this type of file.

3.11.2 Data Block

The Data Block content is a sequence of XML elements described in Table 76.

| XML Tag name | Type | Attributes | C Format | Description |
|-----------------|-------------|--|----------|---|
| FOV_Constraints | XML element | type="mode" being mode one of the following values: Link_to_Spacecraft | - | It defines Field of View constraints, see Table 77. |

Table 76 – Data Block content

| XML Tag name | Type | Attributes | C Format | Description |
|--------------------------|-------------|---|----------|--------------------------------------|
| List_of_Masks | XML element | count="n" being n the number of elements in the list | - | List of Mask elements, see Table 78 |
| Miscellaneous_Parameters | XML element | - | - | Additional parameters, see Table 81. |

Table 77 – FOV_Constraints element content

| XML Tag name | Type | Attributes | C Format | Description |
|--------------|-------------|--|----------|---|
| Mask | XML element | type="mask_type" being mask_type one of the following values: inclusive exclusive | - | It defines a mask in terms of mask points, see Table 79 |

Table 78 – Mask element

| XML Tag name | Type | Attributes | C Format | Description |
|---------------------|-------------|---|----------|---|
| Status | string | - | %s | Mask status. Allowed values: ENABLED DISABLED |
| List_of_Mask_Points | XML element | count="n" being n the number of elements in the list | - | List of Mask_Point elements, see Table 80. |

Table 79 – Mask element content

| XML Tag name | Type | Attributes | C Format | Description |
|--------------|------|------------|----------|-------------|
|--------------|------|------------|----------|-------------|



| | | | | |
|-----------|------|------------|---|-------------------------------|
| Azimuth | real | unit="deg" | - | Azimuth of the point in deg |
| Elevation | real | unit="deg" | - | Elevation of the point in deg |

Table 80 – Mask_Point element content

| XML Tag name | Type | Attributes | C Format | Description |
|---------------|------|------------|----------|-------------------------------------|
| Min_Tg_Height | real | unit="m" | - | Minimum tangent height allowed in m |

Table 81 – Miscellaneous_Parameters element content

Example (only few mask points are shown):

```

<Data_Block type="xml">
  <FOV_Constraints type="Link_to_Spacecraft">
    <List_of_Masks count="2">
      <Mask type="inclusive">
        <Status>ENABLED</Status>
        <List_of_Mask_Points count="4">
          <Mask_Point>
            <Azimuth unit="deg">0.0</Azimuth>
            <Elevation unit="deg">10.0</Elevation>
          </Mask_Point>
          [...]
          <Mask_Point>
            <Azimuth unit="deg">0.0</Azimuth>
            <Elevation unit="deg">-90.0</Elevation>
          </Mask_Point>
        </List_of_Mask_Points>
      </Mask>
      <Mask type="exclusive">
        <Status>ENABLED</Status>
        <List_of_Mask_Points count="8">
          <Mask_Point>
            <Azimuth unit="deg">0.0</Azimuth>
            <Elevation unit="deg">-85.0</Elevation>
          </Mask_Point>
          [...]
          <Mask_Point>
            <Azimuth unit="deg">0.0</Azimuth>
            <Elevation unit="deg">-90.0</Elevation>
          </Mask_Point>
        </List_of_Mask_Points>
      </Mask>
    </List_of_Masks>
    <Miscellaneous_Parameters>
      <Min_Tg_Height unit="m">19000.0</Min_Tg_Height>
    </Miscellaneous_Parameters>
  </FOV_Constraints>
</Data_Block>

```

3.11.3 Schema Reference

An example of validating XML schema for this file type is located at:
http://eop-cfi.esa.int/CFI/EE_CFI_SCHEMAS/EO_OPER_INT_FOVCFG_0300.XSD

This schema is compliant to [RD02] and includes format and range checks to ensure compliance to this specification and to the File Format Standard [RD01]. The schema file is named according to section 6.1.1 in [RD02] and is applicable to files named `MMM_OPER_INT_FOVCFG_<instance_id>.EOF`.

The following is the content of the [Earth_Observation_File](#) required to reference the above schema.

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```
<Earth_Observation_File
  xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
  xsi:schemaLocation="http://eop-cfi.esa.int/CFI http://eop-
cfi.esa.int/CFI/EE_CFI_SCHEMAS/EO_OPER_INT_FOVCFG_0300.XSD"
  xmlns="http://eop-cfi.esa.int/CFI" schemaVersion="3.0">
```

3.12 DEM Generic Raster Configuration File

3.12.1 File naming convention

The **DEM tiles** (i.e. binary height raster data) are named after the **southwestern corner** in degrees. The name will have the following format, without any extension,

XXAYYYB

where:

- XX: numeric latitude of southwestern corner (completed with 0 at the beginning if needed),
- A: N (for North) or S (for South),
- YYY: numeric longitude of southwestern corner (completed with 0 at the beginning if needed),
- B: W (for West) or E (for East).

The **DEM flag files** will have the same name as the corresponding DEM tile but adding the suffix “_flag”.

For example, a tile with southwestern corner at latitude -45 degrees and longitude 30 degrees, the files must be named:

- DEM tile: 45S030E
- DEM flag file: 45S030E_flag

3.12.2 Binary Data Format

The data written in DEM tiles and DEM flag files is binary data with the following characteristics:

- the data is written so that the first row in the file corresponds to the southern-most latitude followed, in row major order, by adjacent northern rows – as shown in the figure Figure 3, for a tile named by its southwesternmost corner 45S030E, the first row of the file contains data for latitude 45° South (i.e. bottom edge of the tile) while the last row of the file contain data for latitude 30° South (i.e. top edge of the tile);
- multibyte data layout is little-endian.

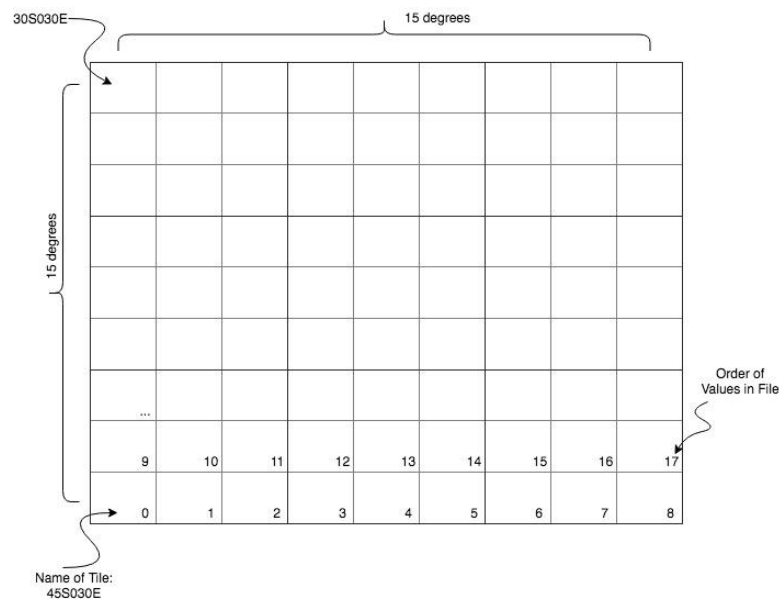


Figure 3 – Order of data for Generic DEM Raster

The description of the data types and sizes is provided in Section 3.12.5.

3.12.3 DEM Raster Configuration File

The DEM raster configuration file must be placed in the same directory as the DEM files. It must have the name:

dem_raster_configuration.xml

This will be the name that the software will look for.

The DEM raster configuration file describes the content of the DEM files. In particular, the following items are listed:

- Data type of the DEM file data.
- Data unit of the stored altitudes.
- Number of rows and columns of the data.
- Angular resolution of the data.
- Reference with respect to which the altitudes are provided (geoid, ellipsoid).
- Value that must be considered as void (no data).
- Data type of the DEM flag file data.

3.12.4 Variable Header

The Variable Header is empty for this type of file.

3.12.5 Data Block

The Data Block content is a sequence of XML elements described in Table 82.

| XML Tag name | Type | Attributes | C Format | Description |
|--------------------------|-------------|------------|----------|---|
| DEM_Raster_Configuration | XML element | - | - | It defines DEM generic raster, see table Table 83 |

Table 82 – Data Block content

| XML Tag name | Type | Attributes | C Format | Description |
|--------------|-------------|--|----------|---|
| Data_Type | XML element | - | %s | Data type of the DEM data. Allowed values: int16 int32 int64 float32 float64 |
| Data_Unit | XML element | - | %s | Unit in which the DEM data is provided. Allowed values: Meter kilometer |
| Rows | | - | %ld | Number of rows in the DEM tile |
| Columns | | - | %ld | Number of columns in the DEM tile |
| Resolution | | unit="data_resolution" being data_resolution one of the following values: deg min sec | %lf | Resolution of DEM data (angular separation between tile adjacent points). |



| | | | | |
|------------|--|---|-----|---|
| Reference | | - | %s | Reference with respect to which the DEM altitudes are provided. Allowed values: WGS84 EGM96 |
| Void_Value | | - | %lf | Value to be considered as void value in DEM data. |
| Flag_Type | | - | %s | Data type of DEM flag file. Allowed values: int8 int16 int32 int64 |

Table 83 – DEM_Raster_Configuration element content

Example:

```
<Data_Block type="xml">
  <DEM_Raster_Configuration>
    <Data_Type>int16</Data_Type>
    <Data_Unit>meter</Data_Unit>
    <Rows>1800</Rows>
    <Columns>1800</Columns>
    <Resolution unit="sec">30</Resolution>
    <Reference>WGS84</Reference>
    <Void_Value>-32768</Void_Value>
    <Flag_Type>int8</Flag_Type>
  </DEM_Raster_Configuration >
</Data_Block>
```

3.12.6 Schema Reference

An example of validating XML schema for this file type is located at:

http://eop-cfi.esa.int/CFI/EE_CFI_SCHEMAS/EO_OPER_MPL_DEMRAS_0300.XSD

This schema is compliant to [RD02] and includes format and range checks to ensure compliance to this specification and to the File Format Standard [RD01]. The schema file is named according to section 6.1.1 in [RD02] and is applicable to files named `MMM_OPER_MPL_DEMRAS_<instance_id>.EOF`.

The following is the content of the [Earth_Observation_File](#) required to reference the above schema.

```
<Earth_Observation_File
  xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
  xsi:schemaLocation="http://eop-cfi.esa.int/CFI http://eop-cfi.esa.int/CFI/EE_CFI_SCHEMAS/EO_OPER_MPL_DEMRAS_0300.XSD"
  xmlns="http://eop-cfi.esa.int/CFI" schemaVersion="3.0">
```